CAESAR KLEBERG WILDLIFE **RESEARCH INSTITUTE** TEXAS A&M UNIVERSITY-KINGSVILLE

Delilah D. Bernal¹, Humberto L. Perotto-Baldivieso¹, Caesar Kleberg Wildlife Research Institute, Texas A&M University-Kingsville, Kingsville, TX 78363, USA¹ Department of Natural Resources Management, Lubbock, TX, 79410, USA²

INTRODUCTION

- Cattle (*Bos Taurus*) play an essential role in shaping the vegetation composition and land structure in their given environments (Butt, 2010; Walker & Heitschmidt, 1986).
- Understanding the behavior of animals requires quantifying their movement and patterns (Ray & Stopfer, 2021).
- There is little information on quantifying cattle movement through identifiable pastoral trails using drones.

OBJECTIVES

- Determine the feasibility of identifying cattle paths across the landscape.
- Determine the density of the cattle trails and the proportion of heavily used trails.

METHODOLOGY

- Our study site was located on a 95.5-ha pasture located at Jim Hogg County, Texas, USA (Fig. 1).
- The data was collected at an altitude of 100 m (AGL) on July 03,2020 (Page, 2022).
- We created an orthomosaic model on Pix4D mappers then input into ArcGIS Pro to outline all identifiable cattle trails (Fig.2) (Pix4D, 2023; ESRI, 2023).
- Stratified 100 random points ranging from 1-50 in radius.
- We used the line density formula to determine the density of the cattle trails within various radiuses (Fig. 3-9).

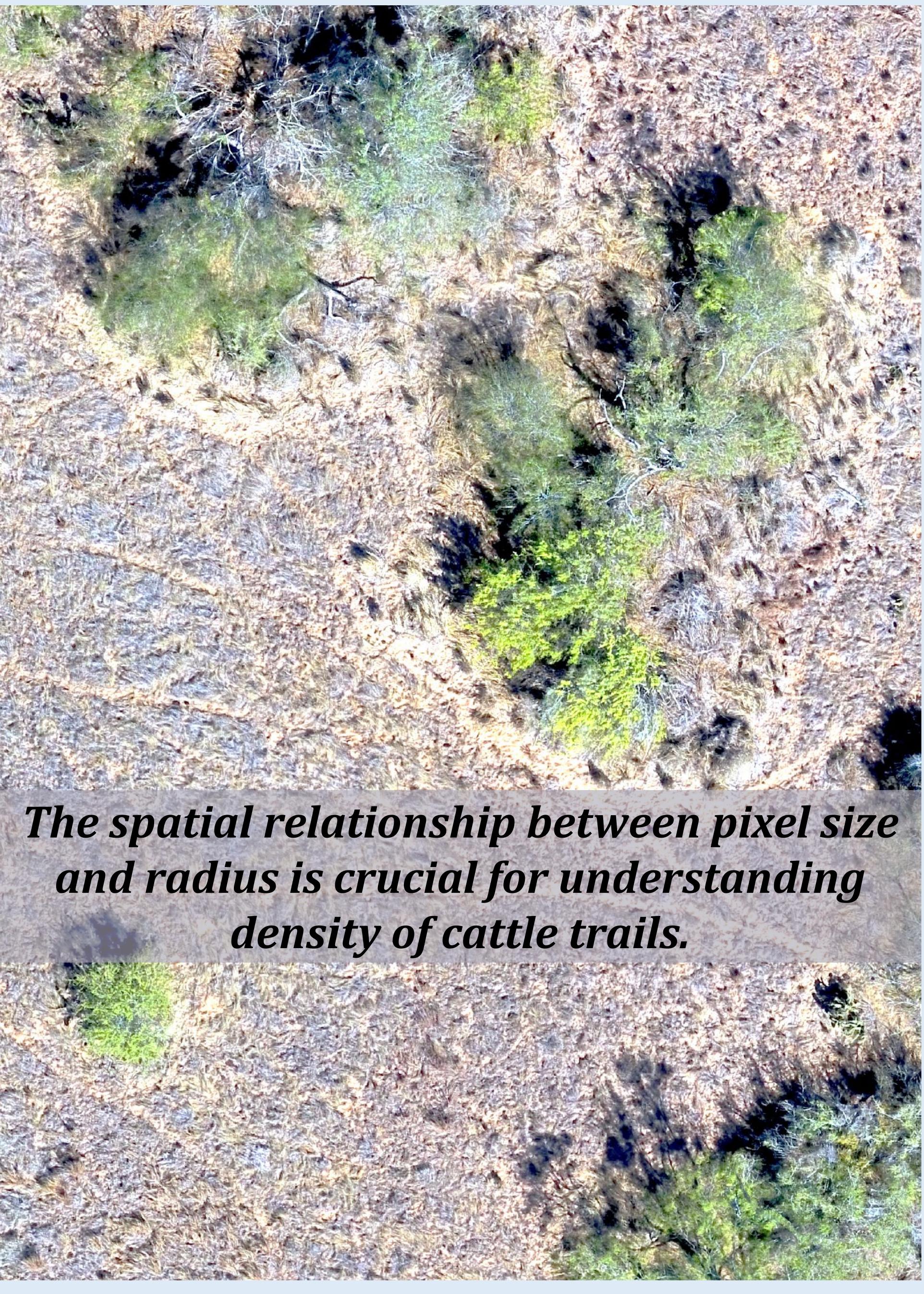
PRELIMINARY RESULTS

- From our analysis, as the radius increased the differences of density in the cattle trails increased.
- However, as the radius continues to increase at a certain range (between 8-15 m) the differences of density decrease and start to get classified together (Fig. 10).

DISCUSSION

- There is limited research in quantifying cattle trails utilizing density.
- Drones provide a way to quantify cattle movement.
- Future analysis is required to determine at which scale the densities will be optimized before being classified together.

Quantifying cattle movement through identifiable pastural trails using unmanned aerial vehicles



Acknowledgments: Funding for this project was provided by the McNairs Scholar Program. Special thanks to my mentor H. L. Perotto-Baldivieso and the following grad students Daniel Ramirez, Silverio Avila and Dakota Moberg. The rotary club of Corpus Christi Harvey Well sportsman conversationalist award



Texas, USA.

Figure 1. Study site



Fig 3. 2 m

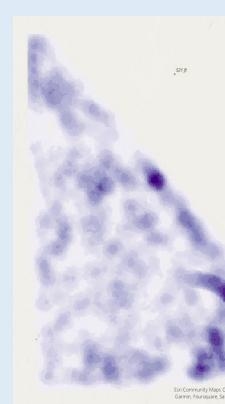
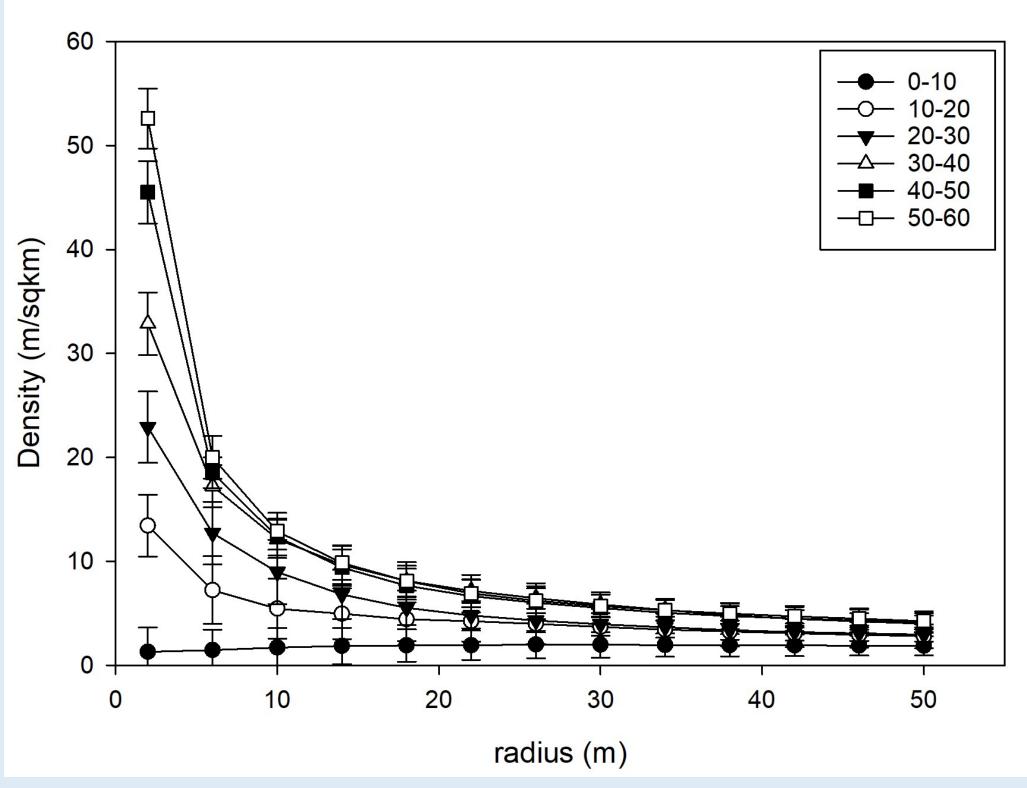


Fig 6. 26 m





MCNAIR SCHOLARS PROGRAM

FIGURES

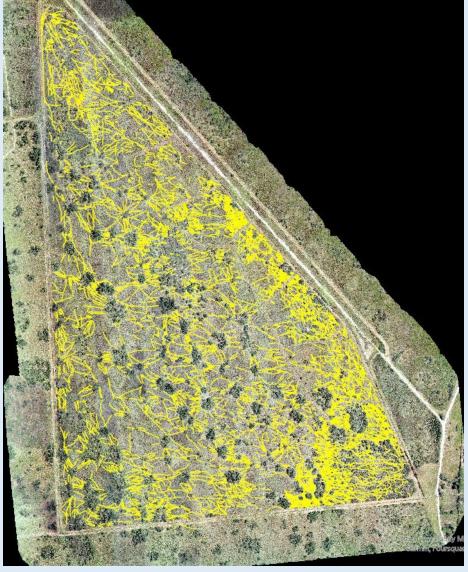


Figure 2. Our 2D orthomosaid model of all identifiable cattle trails

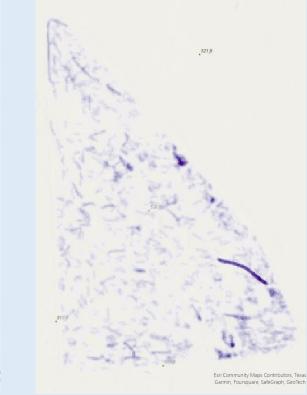


Fig 4. 6 m

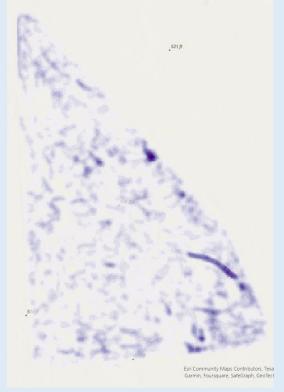


Fig 5. 10 m

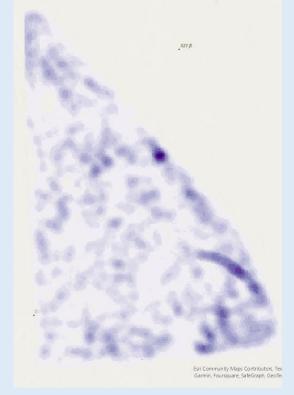


Fig 6. 18 m

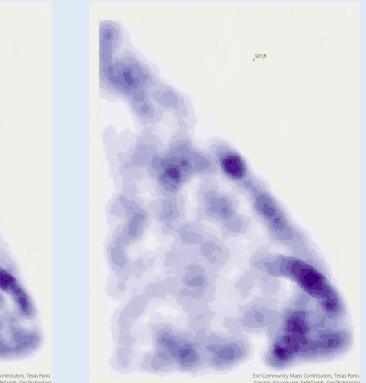


Fig 7. 34 m

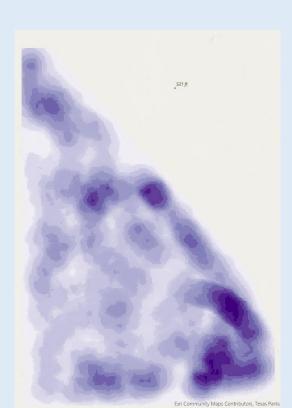


Fig 8. 42 m

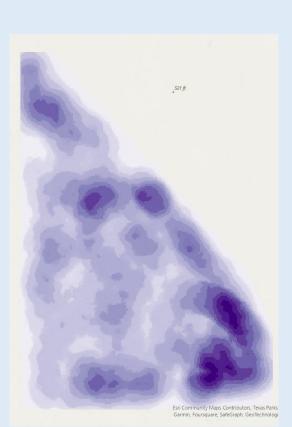


Fig 9. 48 m

Figure 10. Mean and SD of all radius ranges in relation to the density of trails.